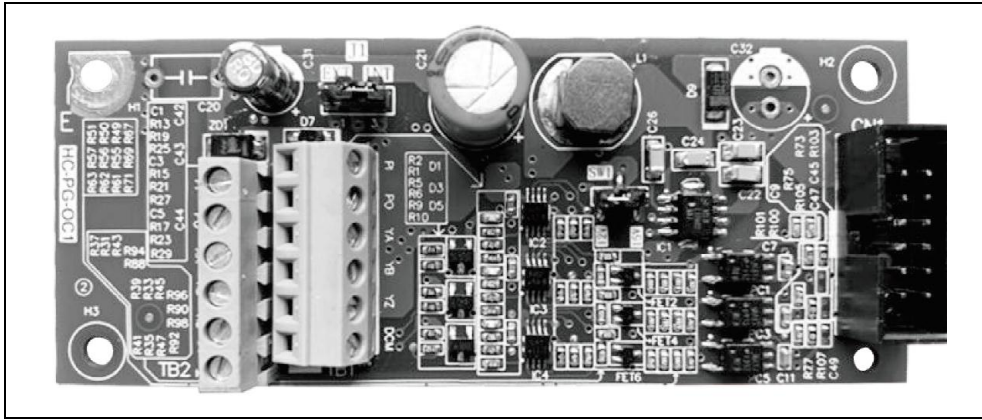


HC-PG-OC1 (12V/15V open collector) S3100 series PG card

Operation manual

Thank you to purchase SAVCH HC-PG-OC1 card. Functions: input pulse train control and velocity feedback.

1. External view



2. Terminal instructions

Terminal	Functions
PI	External encoder input power supply. Input power source: DC+12V±10%, or DC+15V±10% (When Encoder loading current over 120mA, please select external power)
PO	Internal encoder output power supply (Output power source: DC+12V, 120mA, or DC+15V±10%, 120mA)
DCM	Common port for power source and signal.
XA	Instruction side A input terminals
XB	Instruction side B input terminals
XZ	Reserved (Instruction side Z input terminals)
YA	Feedback side A input terminals
YB	Feedback side B input terminals
YZ	Feedback side Z input terminals

Notes:

- Terminal use screw: M2, Cable: AWG16~24, Screw torque: 0.22~0.25N.m.
- After install the card, do not input the pulse train to the inverter terminals [MI7].
- When Encoder loading current over 120mA, please select external power. And the switch J1's jumper put at (EXT) side.
- For factory default, SW1 will be set up to [12V] mode.

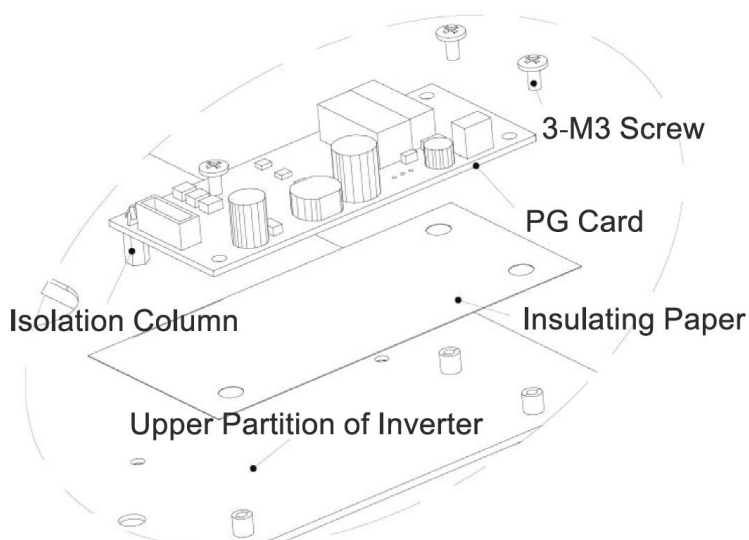
3. Installation, wiring

⚡ Danger

- Before installation and wiring, The power has to be disconnected: under 22kW, it needs to disconnect for more than 5 minutes, more than 30kW, it needs to disconnect for more than 10 minutes, confirm the keypad and the charge indicator has been extinguished, and then use the multimeter to check the voltage which in the main circuit terminal P (+) - N (-) between the DC bus, it has fallen to a safe range below (DC + 25V), finally we can do installation and wiring.

Otherwise there is risk of electric shock.

- The installation sequence of HC-PG-OC1 card is shown in the figure below.
- Use M3 screw which is kind of self-climbing with gasket to lock HC-PG-OC1 card.



4. Applications

4.1 Drive the motor with encoder to control high precision speed

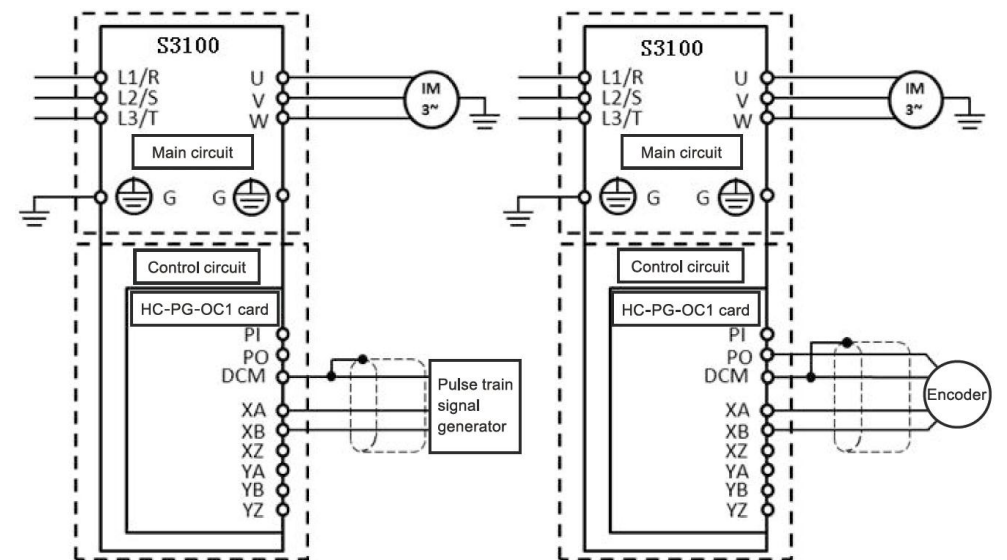
After installed on the motor encoder, can achieve closed-loop vector control. Frequency converter can realize high precision, high response speed control.

4.2 Control performance

The table below for the performance of vector control with velocity feedback.

Item	Performance	Remark
Max.output Hz	25~200Hz (More than 200Hz, the OS alarm will be happened)	Recommend encoder to use: 1024 P/R or higher.
Speed control range	Min. speed: basic frequency=1:1500 (4 pole motor : 1~1500r/min)	
Speed control accuracy	Analog range: ≤±0.2% Max. frequency (15~35°C) Digital range: ≤±0.01% Max. frequency (-10~50°C)	

4.3 Pulse train input wiring Diagram

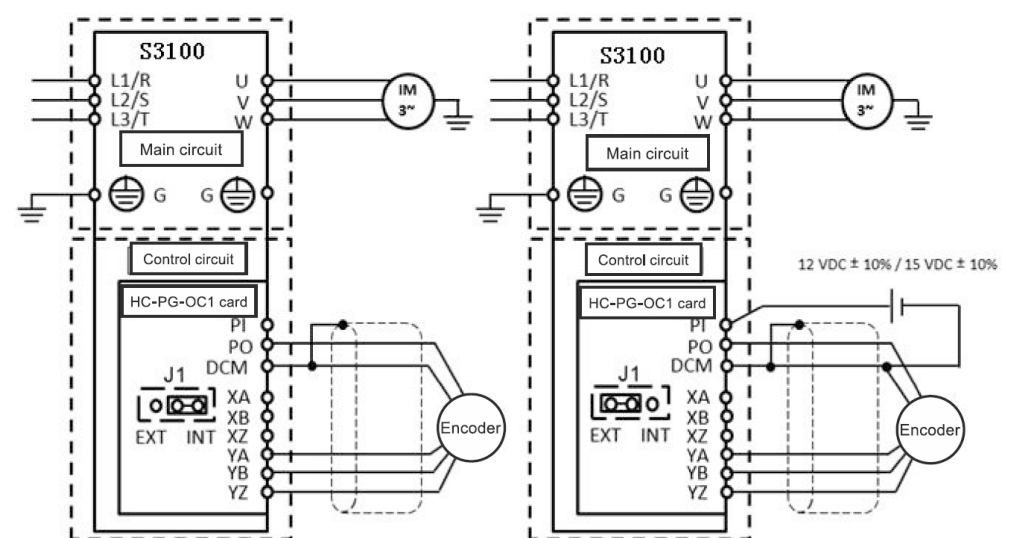


Used pulse train signal generator

Used encoder signal generator

Remark : The signal lines is susceptible by external noise, so for signal lines, please use the shielded wire, and wiring as short as possible (below 20m). The shielding layer of shielding wire is recommended to disconnect on PG side (encoder), make it as one wire to connect DCM on HC-PG-OC1 card .

4.4 Speed control wiring diagram (vector control with the encoder)



Used the inverter internal power wiring diagram
(J1 jumper in the INT position)

Used the inverter external power wiring diagram
(J1 jumper in the EXT position)

Remark :

- The signal lines is susceptible by external noise, so for signal lines, please use the shielded wire, and wiring as short as possible (below 20m). The shielding layer of shielding wire is recommended to disconnect on PG side (encoder), make it as one wire to connect DCM on HC-PG-OC1 card.
- [YZ] it's not use for control signal, actually if you can not find the cable which is for Z phase, so you don't need to connect.

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